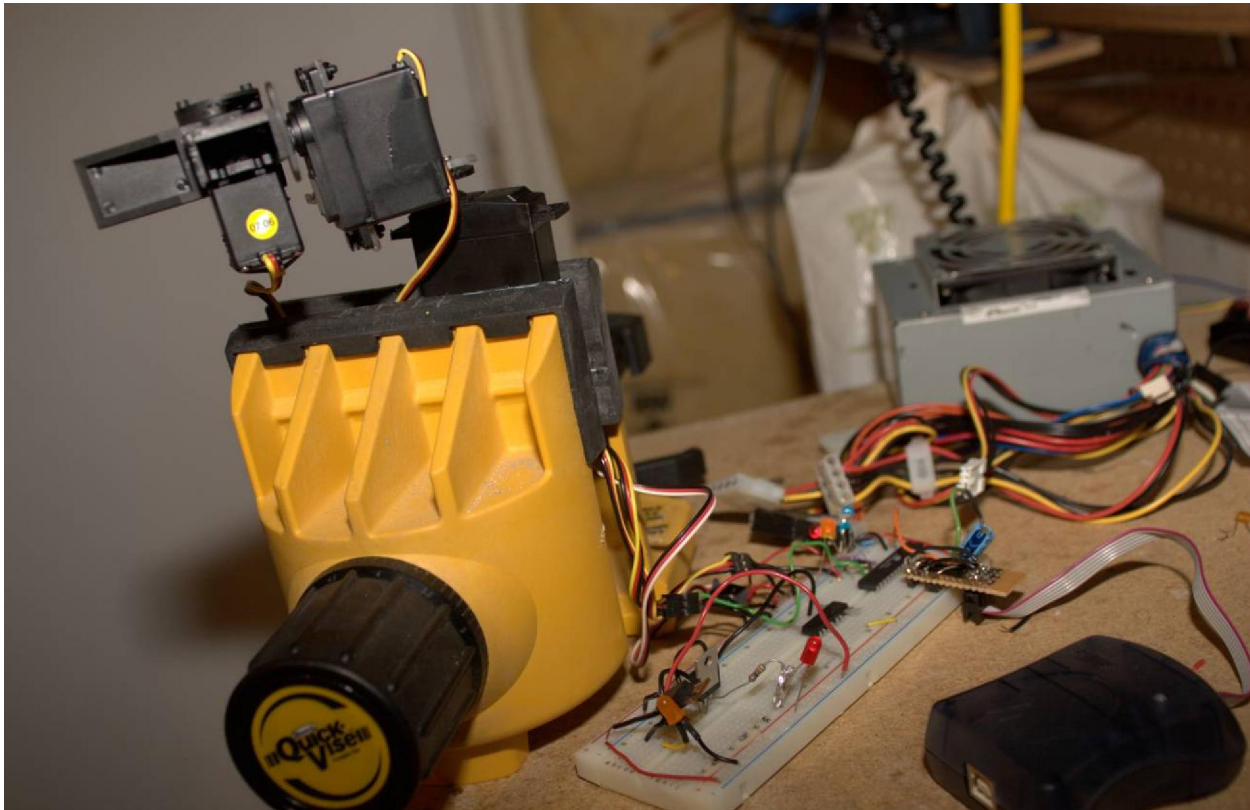
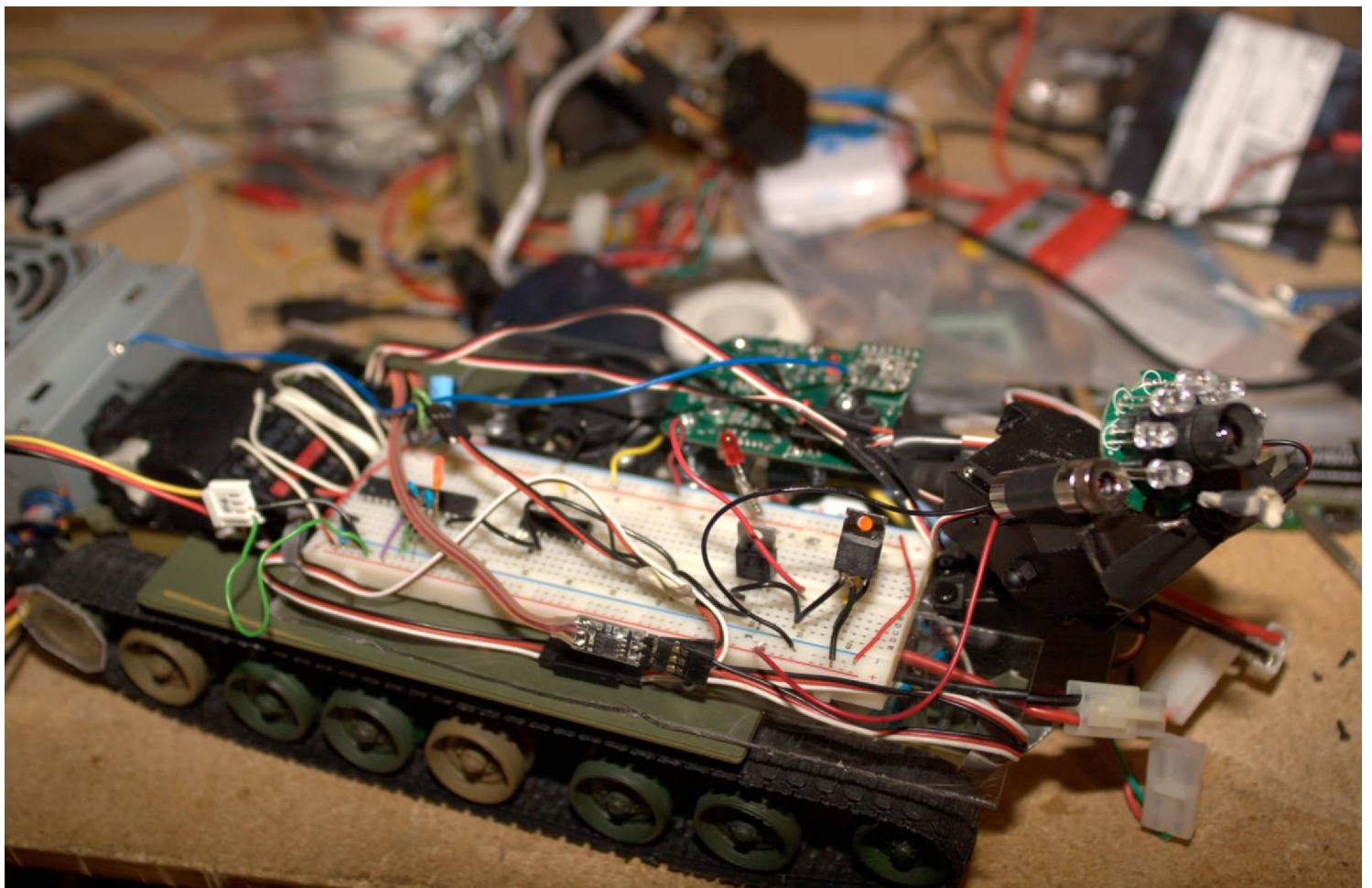


Robot chassis, built from model tank with rechargeable AA cells soldered into packs.



Robotic  
Pincers using  
3 servos.  
Control is  
provided by  
AVR  
ATMega168  
that does  
PWM on 7  
different  
pins.



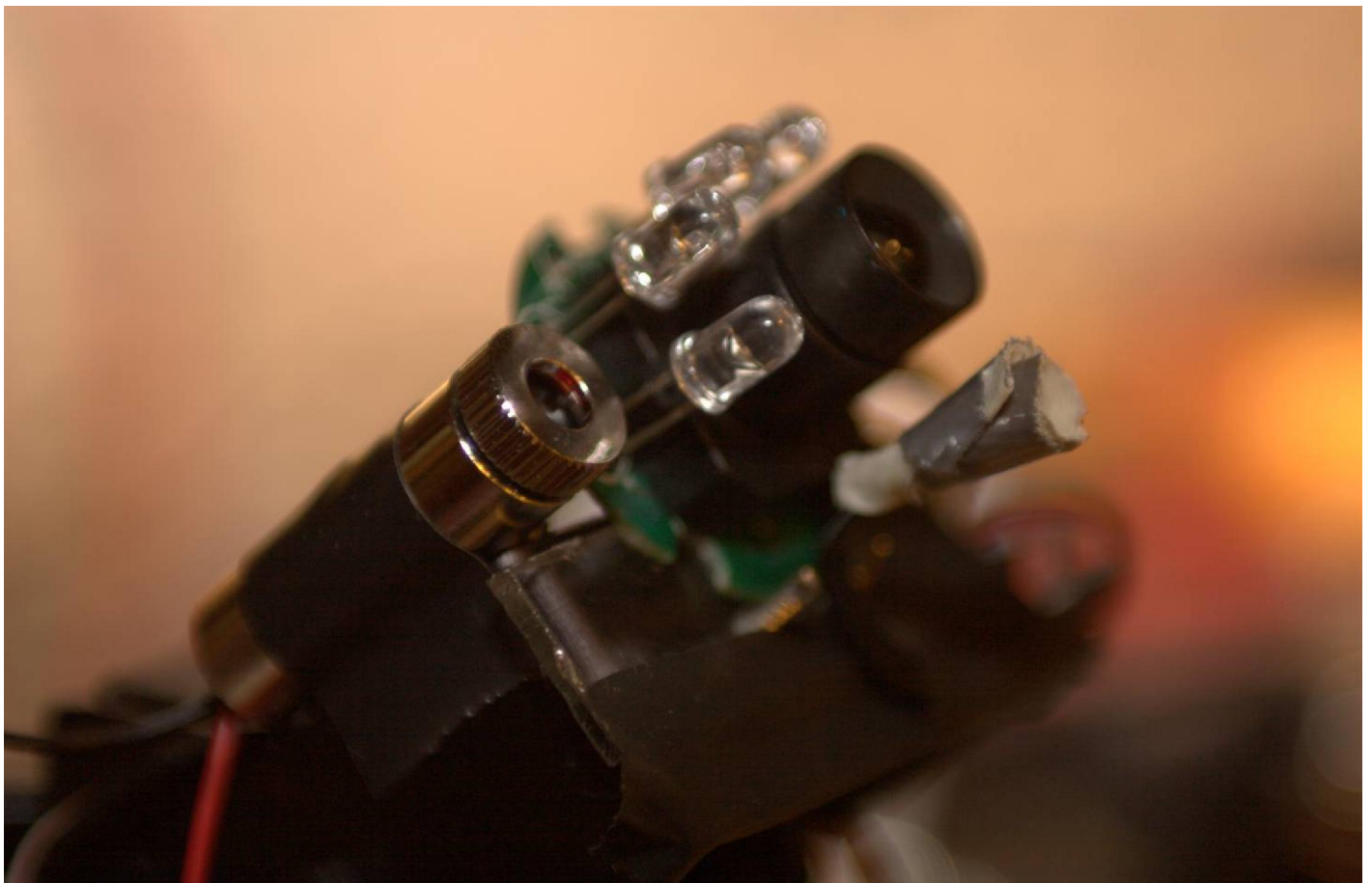


Top: Full body complete up till now

Bottom: Unit with ranging laser activated (steam used to make laser visible)







Top: Optical unit including camera, light sensor (in duct tape), IR LEDs (night lighting), and Laser emitter

Bottom: User control system shown along with full system and image transmitted.

